

## Lecture 6:

### Divergences between Probability measures

#### I Motivating problem: density fitting

- Fundamental problem: compare  $\nu \in \mathcal{P}(\mathbb{R}^d)$  arising from measurements to a model which is a parameterized family of distributions  $\{\mu_\theta ; \theta \in \Theta\}$  where typically  $\Theta \subseteq \mathbb{R}^k$ .

- A suitable parameter can be obtained by minimizing:

$$\min_{\theta \in \Theta} F(\theta) \text{ where } F(\theta) = D(\mu_\theta, \nu) \quad (*)$$

where  $D : \mathcal{P}(\mathbb{R}^d) \times \mathcal{P}(\mathbb{R}^d) \rightarrow [0, +\infty]$  is a divergence.

- In this lecture, by divergence we mean  $\begin{cases} D(\nu, \nu) \geq 0 \\ D(\nu, \nu) = 0 \end{cases}$ .

Example 1: One can choose  $D(\nu, \nu) = W_p^\rho(\nu, \nu)$  for some  $p \geq 1$ .

When  $\nu$  is an empirical measure, with  $p=2$ , the solution to  $(*)$  is called the Minimum Kantorovich Estimator.

Example 2: let  $x_1, \dots, x_n \in \mathbb{R}^d$  are independent samples from  $\nu$ . When  $\mu_\theta$  has a density  $\rho_\theta$  w.r.t a reference measure  $\sigma$ , the maximum likelihood estimator (MLE) is

$$\min_{\theta \in \Theta} -\frac{1}{n} \sum_{i=1}^n \log(\rho_\theta(x_i)) \quad (1)$$

This corresponds to an empirical version of solving  $(*)$  with  $D(\mu_\theta, \nu) = \text{KL}(\mu_\theta, \nu)$  since (1) converges to  $-\int \log(\rho_\theta(x)) d\nu(x) = \text{KL}(\mu_\theta, \nu) - \int \log\left(\frac{d\nu}{d\sigma}\right) d\nu$  (provided all the terms are finite).

- Note that the MLE fails :

- when there is no natural reference measure  $\sigma$
- when  $\rho_\theta$  is difficult to compute
- when the objective  $F$  is too complicated to minimize.

## Generative models

Generative models are when the parametric measure  $\nu_\theta$  is given by

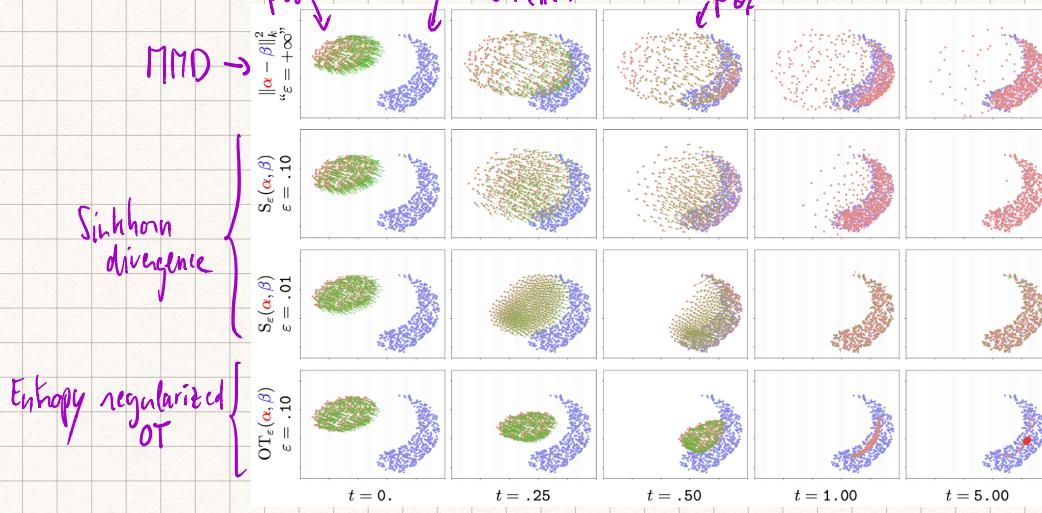
$$\nu_\theta = (h_\theta)_\# \xi \quad \text{where } h_\theta: \mathbb{Z} \rightarrow \mathbb{R}^d$$

and where  $\xi \in \mathcal{P}(\mathbb{Z})$  is a reference measure. This leads to

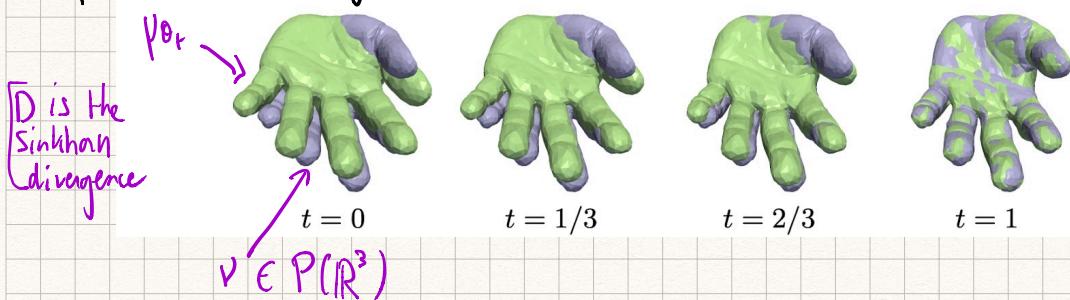
$$F(\theta) = D((h_\theta)_\# \xi, \nu).$$

The typical approach to "minimize"  $F$  is the gradient descent algorithm :

- initialize  $\theta_0 \in \Theta$
- for  $t = 1, 2, \dots$  let  $\theta_{t+1} = \theta_t - \gamma \nabla F(\theta_t)$  formula?



Application to shape registration:



$(h_\theta)_\#$  is a parameterized set of diffeomorphisms.

Let us give a formula for  $\nabla F(\theta)$  under strong regularity assumptions.

Let us denote  $E: \mu \mapsto D(\mu, \nu)$

Proposition. Assume that  $E: \mathcal{P}_2(\mathbb{R}^d) \rightarrow \mathbb{R}$  is such that  $\forall \mu \in \mathcal{P}_2(\mathbb{R}^d)$ , there exists a function  $E'(\mu) \in \mathcal{C}'(\mathbb{R}^d)$  with  $\nabla E'(\mu)$  Lipschitz, and such that  $\forall \nu \in \mathcal{P}(\mathbb{R}^d)$ ,

$$E(\nu) - E(\mu) = \int_{\mathbb{R}^d} E'(\mu) d(\mu - \nu) + o(W_2(\mu, \nu)).$$

Assume moreover that  $h: \mathbb{R}^p \rightarrow L^2(\Sigma; \mathbb{R}^d)$  is (Fréchet) differentiable, with partial derivatives at  $\theta$  denoted  $\partial_i h_\theta \in L^2(\Sigma; \mathbb{R}^d)$ . Then  $F: \theta \mapsto E((h_\theta)_\# \Sigma)$  is

differentiable with gradient, for  $i=1, \dots, p$ ,

$$[\nabla F(\theta)]_i = \int_{\Sigma} \nabla E'((h_\theta)_\# \Sigma)(h_\theta(z))^T \partial_i h_\theta(z) d\Sigma(z). \quad \text{C for digest in the practical session}$$

Proof: First we study  $G: f \mapsto E(f_\# \Sigma)$  and show that  $G$  is (Fréchet) differentiable with differential :  $DG(f)(Sf) = \int \nabla E'(f_\# \Sigma)(f(z))^T Sf(z) d\Sigma(z)$ . Then the conclusion follows by the usual chain rule for Fréchet differentials.

For  $f, Sf \in L^2(\Sigma; \mathbb{R}^d)$ , we have that  $W_2(f_\# \Sigma, (f+Sf)_\# \Sigma) \leq \|Sf\|_{L^2(\Sigma)}$  by taking  $(f, f+Sf)_\# \Sigma$  as an admissible transport plan. Thus,

$$\begin{aligned} E((f+Sf)_\# \Sigma) - E(f_\# \Sigma) &= \int_{\Sigma} [E'(f_\# \Sigma)(f(z)+Sf(z)) - E'(f_\# \Sigma)(f(z))] d\Sigma(z) + o(\|Sf\|) \\ &= \int_{\Sigma} \nabla E'(f_\# \Sigma)(f(z))^T Sf(z) d\Sigma(z) + \underbrace{o(\text{Lip}(\nabla E'(f_\# \Sigma)) \|Sf\|^2)}_{o(\|Sf\|)} + o(\|Sf\|) \end{aligned}$$

This shows  $G(f+Sf) - G(f) = DG(f)(Sf) + o(\|Sf\|)$ . Hence the conclusion  $\blacksquare$

Example: Show if  $W: \mathbb{R}^d \times \mathbb{R}^d \rightarrow \mathbb{R}$  is symmetric and differentiable with a Lipschitz gradient, then  $E(\mu) := \int W(x, y) d\mu(x) d\mu(y)$  satisfies the assumptions above with  $E'(\mu): x \mapsto \int W(x, y) d\mu(y)$ .

Now we will introduce various divergences and study : (i) the "divergence property"

From now,  $X$  is a compact metric space -

(ii) their weak continuity .

## II Csiszár divergences (a.k.a. f-divergences)

Definition. Let  $f: \mathbb{R} \rightarrow \mathbb{R} \cup \{+\infty\}$  be a convex function. For  $\mu, \nu \in \mathcal{P}(X)$ , let  $\mu = \left(\frac{d\mu}{d\nu}\right) \nu + \mu^\perp$  be the Lebesgue decomposition. We define

$$D_f(\mu, \nu) = \int f\left(\frac{d\mu}{d\nu}\right) d\nu + f'_\infty(1) \cdot \mu^\perp(X)$$

where  $f'_\infty(x) := \lim_{t \rightarrow +\infty} f(tx)/t \in \mathbb{R} \cup \{+\infty\}$ .

↳ recession/horizon of f

Proposition: Let  $f$  be convex and such that  $\min f = 0$  and  $\operatorname{argmin} f = \{1\}$ .

Then  $D_f(\mu, \nu) \geq 0$  with equality if and only if  $\mu = \nu$ .

Proof: If  $\mu = \nu$  then  $\frac{d\mu}{d\nu} = 1 \in L^1(\nu)$  and  $\mu^\perp = 0$  so  $D_f(\mu, \nu) = \int f(1) d\nu = 0$ .

Conversely if  $D_f(\mu, \nu)$  then  $\mu^\perp = 0$  (because  $f'_\infty(1) \geq f(z) - f(1) > 0$ ) and

$\frac{d\mu}{d\nu} = 1 \in L^1(\nu)$  so  $\mu = \nu$ .

Example (Kullback-Leibler divergence). Take  $f(s) = \begin{cases} s \log s - s + 1 & \text{if } s > 0 \\ 1 & \text{if } s = 0 \\ +\infty & \text{if } s < 0 \end{cases}$

If  $\mu \ll \nu$  then

$$D_f(\mu, \nu) = \int_X \left( \frac{d\mu}{d\nu} \log \left( \frac{d\mu}{d\nu} \right) - \frac{d\mu}{d\nu} + 1 \right) d\nu = \int_X \log \left( \frac{d\mu}{d\nu} \right) d\nu = KL(\mu, \nu),$$

and  $D_f(\mu, \nu) = +\infty$  otherwise since  $f'_\infty(1) = +\infty$ .

Example (Total variation). Take  $f(s) = \begin{cases} |s - 1| & \text{if } s \geq 0 \\ +\infty & \text{otherwise} \end{cases}$

We have  $f'_\infty(1) = 1$  thus

$$D_f(\mu, \nu) = \int_X \left( \left| \frac{d\mu}{d\nu} - 1 \right| d\nu + d\mu^\perp \right) \stackrel{(*)}{=} \int_X d|\mu - \nu| = |\mu - \nu|(X) = \|\mu - \nu\|_{TV}$$

$= \sup_{f \in \mathcal{C}_b(X)} \{ \int_X f d(\mu - \nu); \|f\|_\infty \leq 1 \}$

where  $(*)$  comes from the fact that  $\begin{cases} (\mu - \nu)_+ = \max\{0, \frac{d\mu}{d\nu} - 1\} \nu + \mu^\perp \\ (\mu - \nu)_- = \max\{0, 1 - \frac{d\mu}{d\nu}\} \nu \end{cases}$ .

In the context of generative models, a drawback is that  $D_f$  is not weakly continuous in general: for instance  $D_f(\delta_x, \delta_y) = \begin{cases} 0 & \text{if } x = y \\ f'_\infty(1) & \text{if } x \neq y \end{cases}$  is discontinuous in general.

Proposition. If  $f: \mathbb{R} \rightarrow \mathbb{R} \cup \{\infty\}$  is convex, l.s.c and not identically  $\infty$ , then  $D_f(\mu, \nu)$  is (jointly) convex, weakly l.s.c and one has

$$D_f(\mu, \nu) = \sup_{\varphi, \psi \in C(X)} \int \varphi d\mu + \int \psi d\nu \text{ s.t. } \varphi(x) + f^*(\psi(x)) \leq 0, \forall x \in X$$

where  $f^*: S \mapsto \sup_{u \in \text{EF}} u \cdot S - f(u)$  is the convex conjugate of  $f$ .

Proof: see the lecture notes.

### III Integral Probability Metrics (dual norms)

Definition: For a symmetric set  $B$  of measurable functions  $X \rightarrow \mathbb{R}$  and  $\alpha \in \mathcal{M}(X)$  a signed finite measure, let

$$\|\alpha\|_B := \sup_{f \in B} \int_X f(x) d\alpha(x)$$

For  $\mu, \nu \in \mathcal{P}(X)$ , with  $\alpha = \mu - \nu$ , we define

$$D_B(\mu, \nu) := \|\mu - \nu\|_B = \sup_{f \in B} \int_X f(x) d(\mu(x) - \nu(x))$$

This is called an "integral probability metric".

Proposition: If  $B$  is symmetric, bounded is sup-norm and contains 0, then  $\|\cdot\|_B$  is a semi-norm on  $\mathcal{M}(X)$ , i.e it is non negative, positively 1-homogeneous and subadditive.

Proof: left as an exercise.

Example 1: Total variation is recovered with  $B = \{f \in C(X); \|f\|_\infty \leq 1\}$ .

Example 2: Wasserstein-1 ( $W_1$ ) is recovered with  $B = \{f \in C(X); \text{Lip}(f) \leq 1\}$ .

Example 3: The "flat norm" corresponds to

$$B = \{f \in C(X); \text{Lip}(f) \leq 1 \text{ and } \|f\|_\infty \leq 1\}$$

To "metrize" the weak convergence,  $B$  should not be too large nor too small.

Proposition 3.5.

- (i) If  $C(X) \subset \overline{\text{span}(B)}^{\|\cdot\|_\infty}$ , i.e. the span of  $B$  is dense in  $(C(X), \|\cdot\|_\infty)$  then  
 $\left\{ \|\alpha_n - \alpha\|_B \rightarrow 0 \text{ implies } \alpha_n \rightarrow \alpha \right.$   
 $\left. (\alpha_n) \text{ bounded for } \|\cdot\|_\infty \right.$
- (ii) If  $B \subset C(X)$  is compact then  
 $\left\{ \alpha_n \rightarrow \alpha \right.$   
 $\left. \alpha_n \text{ bounded for } \|\cdot\|_\infty \right.$  implies  $\|\alpha_n - \alpha\|_B \rightarrow 0$

Proof:

(i) If  $\|\alpha_n - \alpha\|_B \rightarrow 0$ , then  $\forall f \in B$ , since  $\langle f, \alpha_n - \alpha \rangle \leq \|\alpha_n - \alpha\|_B$   
so  $\langle f, \alpha_n \rangle \rightarrow \langle f, \alpha \rangle$ . By linearity, this extends to  $\text{span}(B)$  and then  
to  $\overline{\text{span}(B)}^{\|\cdot\|_\infty}$  since  $|\langle f, \alpha_n \rangle - \langle f', \alpha_n \rangle| \leq \|f - f'\|_\infty \cdot \sup_n \|\alpha_n\|_\infty$ .

(ii) We assume that  $\alpha_n \rightarrow \alpha$ , consider a subsequence  $(\alpha_{n_k})_k$  such that  
 $\|\alpha_{n_k} - \alpha\|_B \rightarrow \limsup \|\alpha_n - \alpha\|_B$

Since  $B$  is compact, let  $f_{n_k} \in B$  achieve the supremum defining  $\|\alpha_{n_k} - \alpha\|_B$ .

We again extract a subsequence  $(f_{n_{k'}}) \xrightarrow{\|\cdot\|_\infty} f \in C(X)$ . One has:

$$\|\alpha_{n_k} - \alpha\|_B = \langle \alpha_{n_k} - \alpha, f \rangle + \langle \alpha_n, f_{n_k} - f \rangle - \langle \alpha, f_{n_k} - f \rangle \rightarrow 0 \blacksquare$$

↳ This is a direct generalization of our proof of weak continuity of  $W_1$  (in lecture 4).

## IV Sinkhorn divergence

### IV.1 Entropy Regularized optimal transport

Def (lecture 3). With  $c \in \mathcal{C}(X \times X)$ , let  $\lambda \geq 0$  be the regularization, and

$$T_{c,\lambda}(\mu, \nu) := \min_{\gamma \in \Pi(\mu, \nu)} \int_X c(x, y) d\gamma(x, y) + \lambda KL(\gamma, \mu \otimes \nu)$$

differ by 1 from the one in  
lecture 3

Reminders:

$$(\text{duality}) \quad T_{c,\lambda}(\mu, \nu) = \sup_{\varphi, \psi \in \mathcal{S}(X)} \int \varphi d\mu + \int \psi d\nu + \lambda \left( 1 - \int \int e^{(\varphi(x) + \psi(y) - c(x, y)) / \lambda} d\mu(x) d\nu(y) \right)$$

(optimality condition) - There exists maximizers  $(\varphi_\lambda, \psi_\lambda)$  and a unique minimizer  $\gamma_\lambda$ ,

$$\text{linked by: } d\gamma_\lambda(x, y) = e^{(\varphi_\lambda(x) + \psi_\lambda(y) - c(x, y)) / \lambda} d\mu(x) d\nu(y)$$

$$\text{In particular, we have: } T_{c,\lambda}(\mu, \nu) = \int \varphi_\lambda d\mu + \int \psi_\lambda d\nu.$$

### IV.2 Is $T_{c,\lambda}$ a suitable divergence?

Proposition: For  $\mu, \nu \in \mathcal{P}(X)$ ,  $c \in \mathcal{C}(X \times X)$ , it holds:

sec lecture 3

$$T_{c,\lambda}(\mu, \nu) \rightarrow \begin{cases} T_c(\mu, \nu) := T_{c,0}(\mu, \nu) & \text{as } \lambda \rightarrow 0 \\ \int c(x, y) d\mu(x) d\nu(y) & \text{as } \lambda \rightarrow +\infty \end{cases}$$

Moreover,  $\gamma_\lambda \rightarrow \mu \otimes \nu$  as  $\lambda \rightarrow +\infty$ .

lecture notes.

Proof: see lecture notes.

$$x^* = \int y d\nu(y) \text{ if } c(x, y) = \|y - x\|_2^2$$

Corollary: Let  $v \in \mathcal{S}(X)$  be such that  $\arg \min_{y \in X} \int c(x, y) d\nu(y)$  is a singleton  $\{x^*\}$ , and let

$$\mu_\lambda \in \arg \min_{\mu} T_{c,\lambda}(\mu, v).$$

Then as  $\lambda \rightarrow +\infty$ , one has  $\mu_\lambda \rightarrow \delta_{x^*}$ .

(Proof sec lecture notes).

### IV.3 Debiased quantity: the Sinkhorn divergence

Thinking of  $-T_{c,\lambda}$  as an "inner product" suggests to define

$$\underline{S_{c,\lambda}(\mu, \nu)} := T_{c,\lambda}(\mu, \nu) - \frac{1}{2} T_{c,\lambda}(\mu, \mu) - \frac{1}{2} T_{c,\lambda}(\nu, \nu)$$

Sinkhorn  
divergence

Proposition (Interpolation properties). - It holds, if  $c(x, y) = \text{dist}(x, y)^p$  for  $p \geq 1$ ,

$$S_{c,\lambda}(\mu, \nu) \rightarrow \begin{cases} T_c(\mu, \nu) & \text{as } \lambda \rightarrow 0 \\ \frac{1}{2} \|\mu - \nu\|_{-c} & \text{as } \lambda \rightarrow \infty \end{cases}$$

where  $\|\cdot\|_{-c}$  is the kernel norm associated to  $-c$ .

(Proof is immediate from the previous proposition).

Proposition . If  $k(x, y) = e^{-c(x, y)/\lambda}$  is a p.d. kernel, then  
 $S_\lambda(\mu, \nu) \geq 0$  with equality if  $\mu = \nu$ .

. If  $e^{-c/\lambda}$  is furthermore a universal kernel, then

$$S_\lambda(\mu_n, \mu) \rightarrow 0 \quad \text{if and only if } \mu_n \rightarrow \mu.$$